

# The SPIN Model Checker

## **Metodi di Verifica del Software**

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**Lezione 2**

**2013**

**Slides per gentile concessione di Gerard J. Holzmann**

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# process synchronization with provided clauses

```
bool toggle = true;          /* global variable          */
short cnt;                   /* default initial value 0 */

active proctype A() provided (toggle == true )
{
L:    cnt++;                  /* increment cnt by 1 */
    printf("A: cnt=%d\n", cnt);
    toggle = false; /* yield control to B */
    goto L
}

active proctype B() provided (toggle == false)
{
L:    cnt--;                  /* decrement cnt by 1 */
    printf("B: cnt=%d\n", cnt);
    toggle = true; /* yield control to A */
    goto L
}
```

← assignment

← print statement

← assignment

← control-flow

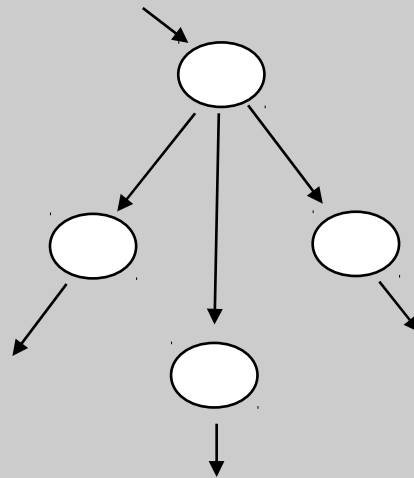
```
$ spin toggle.pml | more
A: cnt = 1
   B: cnt = 0
A: cnt = 1
   B: cnt = 0
A: cnt = 1
   B: cnt = 0
...
```

true == 1  
false == 0

- a process can only execute statements if its provided clause evaluates to true
- the default provided clause is true

# basic statements

- basic statements define the primitive state transformers in Promela
- they end up labeling the edges (transitions) in the underlying finite state automata
- there is only a very small number of *basic* statements in Promela



states and state transformers

# 6 types of basic statements

- assignment: `x++, x--, x = x+1, x = run P()`
- expression statement: `(x), (1), run P(), skip, true, else, timeout`
- print: `printf("x = %d\n", x)`
- assertion: `assert(1+1==2); assert(false)`
- send: `q!m`
- receive: `q?m`

# executability of basic statements

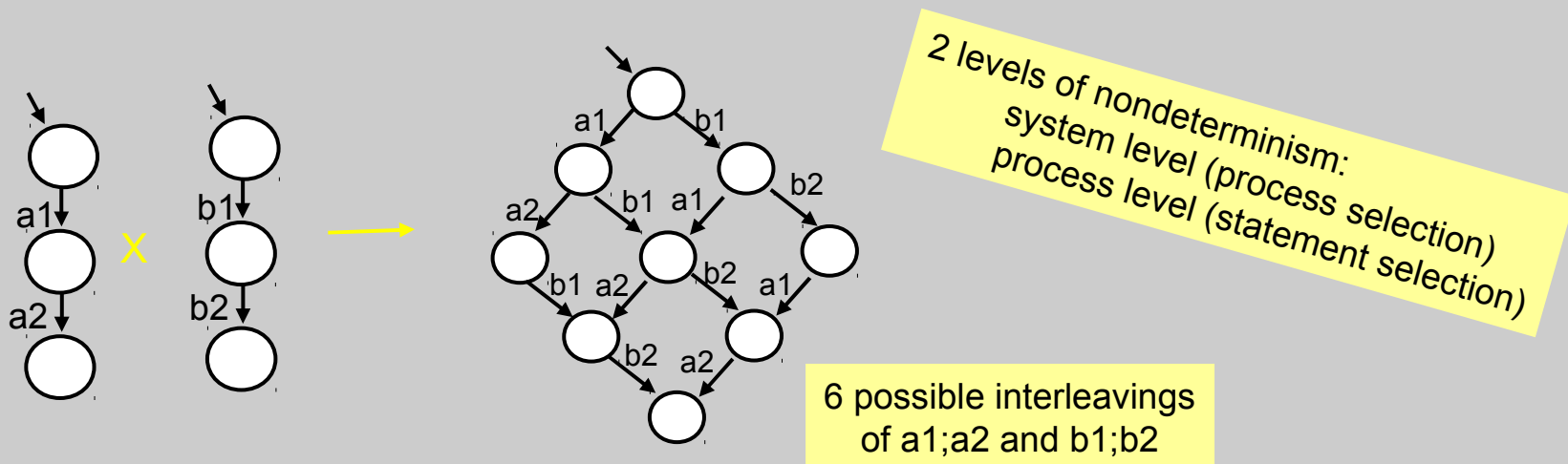
the executability of a statement may depend on the global state of the system

- a Promela statement is either
  - **executable** the statement *can* be executed, or
  - **blocked** the statement *cannot* be executed (yet)
- **3** types of basic statements we have already seen
  - **print** statements
    - always unconditionally executable, no effect on state
  - **assignment** statements
    - always unconditionally executable, changes value of precisely one variable, specified on the left-hand side of the '=' operator
  - **expression** statements
    - executable only if expression evaluates to non-zero (*true*)

$2 < 3$	is always executable
$x < 27$	executable iff the value of $x$ is less than 27
$3 + x$	executable iff $x$ is not equal to $-3$

# statement interleaving

- processes execute concurrently and asynchronously
  - there can be an arbitrarily long pause in between any two statement executions within a process
- process *scheduling* decisions are non-deterministic
- statement executions from different processes are arbitrarily interleaved in time
  - basic statements execute atomically
- local choice within processes can also be non-deterministic



# executability

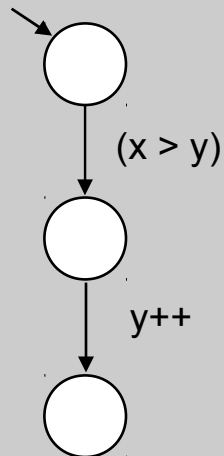
*expression statements* are first-class citizens in Promela  
an expression statement can be used as a synchronizer:  
it is executable only if it evaluates to non-zero (true)

where in C one would write:

```
while (x <= y)
    /* wait */;
y++;
```

in Promela this becomes:

```
(x > y) -> y++
```



synchronizer  
through executability rule

# pseudo statements

- some pseudo-statements:
  - **skip** – always executable, no effect, same as expression (1)
  - **true** – always executable, no effect on state, same as expression (1)
- there is no “run *statement*” – **run** is an *operator* that can appear in restricted expression statements...
  - returns 0 if the max nr of processes would be exceeded by the creation of a new process (the number of processes is bounded)
  - returns the pid of the new process otherwise

```
int x;          /* the default initial value of x is 0 */
proctype A()
{ int y=1;

  skip;
  run B();
  x=2;
  (x>2 && y==1);
  printf("x %d, y %d\n", x, y)
}
```

executable only if **B** can be created

can become executable only if **another process** changes the value of global variable **x**



# run expressions are special

- a **run** operator can only be used in *special* expressions
- all **run**-free expressions in Promela are side-effect free
  - they can be evaluated without causing a change of state
  - unlike in C, e.g. where one could say: `(x++ <= --y)`
- there can be only one **run** operator in an expression and if there is one, there can be no other clauses; ruling out:
  - `(run B() && run A())` could fail with partial side-effect
  - `!(run B())` same as expr: `(_nr_pr >= 255)`
  - `run B() && (a > b)` could start an arbitrary number of copies of `B()` while `(a <= b)`
- it is typically a modeling *error* if **run** can ever return 0

# another type of basic statement (#4)

- **assert**(*expression*)
  - an *assertion statement* is always executable and has no effect on the state of the system when executed
  - Spin reports a *error* if the expression can evaluate to zero (false),
  - the assertion statement can be used to check *safety properties* (properties of local process states or global system states)

```
int n;  
  
active proctype invariant()  
{  
    assert(n <= 3)  
}
```

this process has only one executable statement – because it is an *asynchronous* process, this statement might be executed at any time – it need not execute immediately this is precisely the capability we want in verification, when checking a system invariant condition: it should hold no matter when the assertion is checked the model checker will make sure this is true

# example: mutual exclusion

*allow only 1 process in a critical section at a time  
without relying on a hardware test&set instruction*

```
bool busy;  
byte mutex;
```

```
/* signal entering/leaving the section */  
/* counts # procs in critical section */
```

```
proctype P(bit i)
```

```
{ (!busy) -> busy = true;  
  mutex++;  
  printf("P%d in critical section\n", i);  
  mutex--;  
  busy = false;  
}
```

```
/* wait for busy to be false, then set it to true */
```

```
active proctype invariant()  
{ assert(mutex <= 1);  
}
```

a potential race condition:  
both processes can evaluate  
(!busy) before setting it to false

no loop required

```
init {  
  atomic { run P(0); run P(1) }  
}
```

start two instances of P atomically

# a model checking run

```
$ spin -a mutex1  
$ gcc -DSAFETY -o pan pan.c  
$ ./pan
```

# guided simulation of the counter-example that was generated

```
$ spin -t -p mutex1
```

# Peterson's algorithm (1981)

```
mtype = { A_Turn, B_Turn };
bool x, y;      /* signal entering/leaving the section */
byte mutex;    /* # of procs in the critical section */
mtype turn = A_Turn; /* who's turn is it? */

active proctype A()
{ x = true;
  turn = B_Turn;
  (!y || turn == A_Turn) ->
  mutex++;
  /* critical section */
  mutex--;
  x = false;
}

active proctype B()
{ y = true;
  turn = A_Turn;
  (!x || turn == B_Turn) ->
  mutex++;
  /* critical section */
  mutex--;
  y = false;
}

active proctype invariant()
{ assert(mutex <= 1);
}
```

# basic data types

(book, Table 3.1 p. 41)

Type	Typical Range	Sample Declaration
bit	0..1	bit turn = 1;
bool	false..true	bool flag = true;
byte	0..255	byte cnt;
chan	1..255	chan q;
mtype	1..255	mtype msg;
pid	0..255	pid p;
short	$-2^{15}..2^{15}-1$	short s = 100;
int	$-2^{31}..2^{31}-1$	int x = 1;
unsigned	$0..2^n-1$	unsigned u : 3;

3 bits of storage  
range 0..7

the default initial value of *all* data objects (global *and* local) is zero

all variables (local and global) must be declared before they are used  
a variable declaration can appear anywhere...

note: there are no reals, floats, or pointers  
deliberately: verification models are meant to  
model *coordination* not *computation*

# mtype declarations

(originally used for: *message type* declarations)

- a way to introduce symbolic constant values
- mtype declaration:

```
mtype = { apple, pear, banana, cherry };  
mtype = { ack, msg, err, interrupt }; /* up to 255 names total */
```

- declaring variables of type mtype:

```
mtype a; /* uninitialized, value 0 */  
mtype b = pear; /* value always non-zero */
```



# expression evaluation

- all expressions are evaluated in the widest type (int)
- in assignments and message passing operations, the resulting value is mapped (truncated) to the target type *after* evaluation
  - the Spin *simulator* warns if there is loss of information
  - the Spin *parser* rejects only grievous type errors

```
mtype = { apple, pear };

active proctype tryme()
{
  byte x;
  short y = 1024;
  chan a, b;
  mtype p;

  a = a+b; /* no good -- error */
  x = 257; /* information loss -- warning */
  x = y; /* information loss -- warning */
  p = y/8; /* dubious, but no warning... */
}
```

# arrays and user-defined data types

one-dimensional arrays:

```
byte a[27];  
bit  flags[4] = 1;
```

all array elements are initialized to the same value  
(default 0)

as in C, array indices start at 0

user-defined data types:

```
typedef record {  
    short f1;  
    byte  f2 = 4;  
}
```

```
record rr;  
rr.f1 = 5
```

keyword

name of user-defined data type

default initial value is again 0

declaration of a variable of the  
newly defined type

reference to a structure element

# an indirect way to define multi-dimensional arrays with typedefs and macros

```
typedef array { byte b[4]; }  
array a[4];  
  
a[3].b[2] = 1;
```

or alternatively:

```
#define ab(x,y)  a[x].b[y]  
  
ab(3,2) = ab(2,3) + ab(3,2)
```

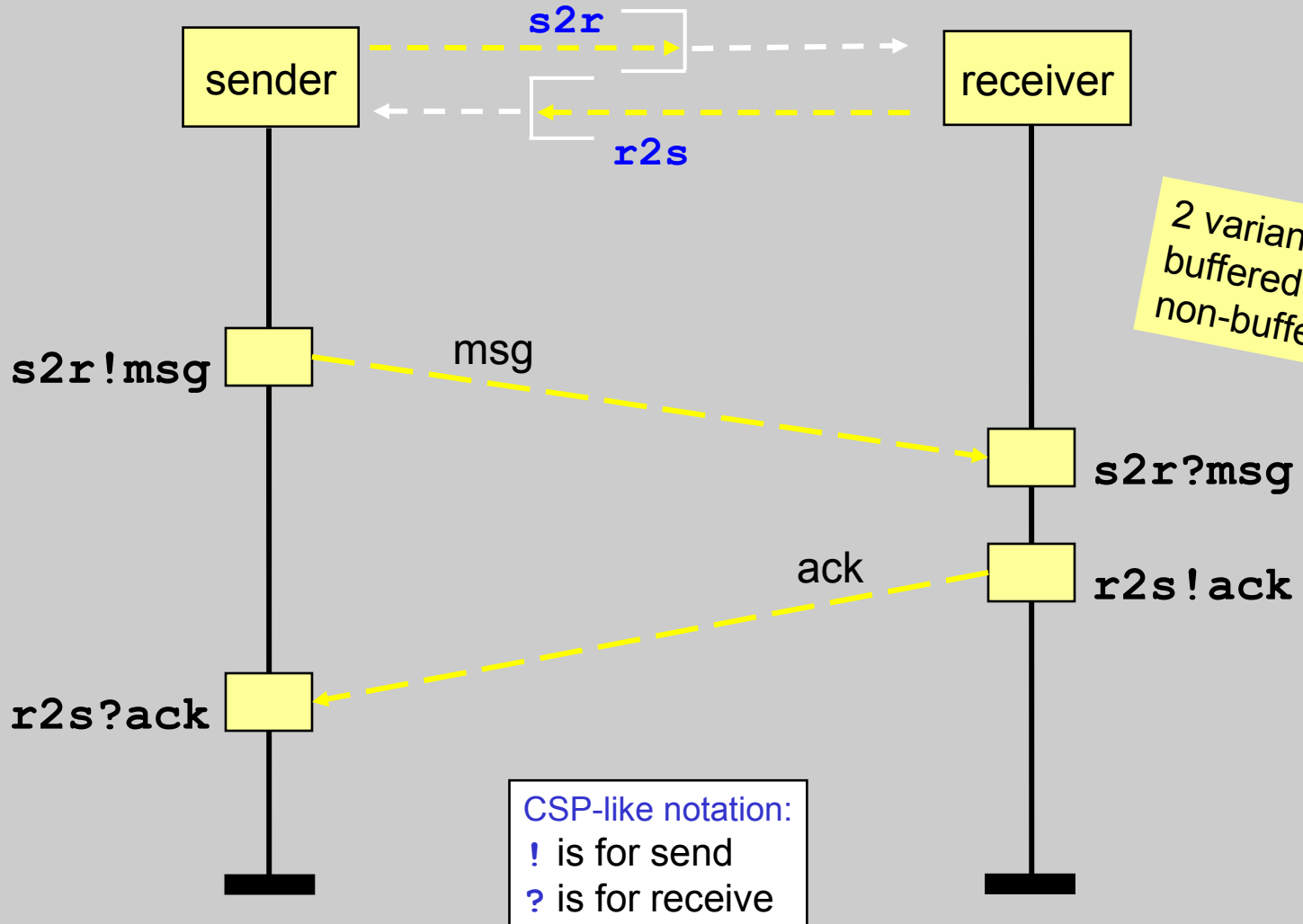
the standard C preprocessor is used  
to preprocess all models before parsing

supports:

```
#define .. ..  
#if ..  
#ifdef ..  
#ifndef ..  
#include "..."
```

etc.

# the last two types of basic statements: send and receive



# message channels

- message passing takes place via *channels* (bounded queues/buffers) either buffered (asynchronously) or unbuffered (by synchronous *rendezvous* handshake)

type name    variable name    initializer

```
chan x = [10] of {int, short, bit};
```

maximum nr of msgs the channel can store  
zero defines a rendezvous channel

structure of messages that can be sent through the channel  
a list of type names: one for each field in the message

uninstantiated channel variable a

a rendezvous channel c

```
chan a;  
chan c      = [0] of {bit};  
chan toR    = [2] of {mtype, bit, chan};  
chan line[2] = [1] of {mtype, record};
```

channels can be sent  
across channels

an array of 2 channels

a user-defined type

# send and receive

send: ch!expr<sub>1</sub>, ... expr<sub>n</sub>

- values of expr<sub>i</sub> correspond to the types from the chan declaration
- *executable* if the target channel is *not full*

receive: ch?const<sub>1</sub> or var<sub>1</sub>, ... const<sub>n</sub> or var<sub>n</sub>

- var<sub>i</sub> fields are set to the value from the corresponding field in the message
- const<sub>i</sub> fields are constraints on the corresponding fields that must be matched
- *executable* when the target channel is *not empty* and the first message matches all constant fields in the receive

example:

```
#define ack 5
```

```
chan ch = [N] of { int, bit };
```

```
bit seqno;
```

```
ch!ack,0;
```

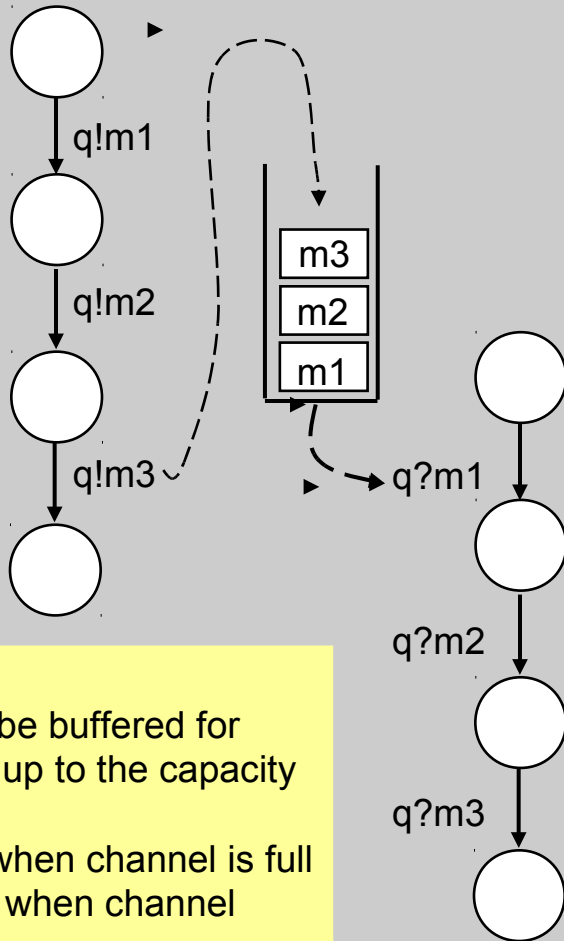
```
ch?ack,seqno
```

alternatively:

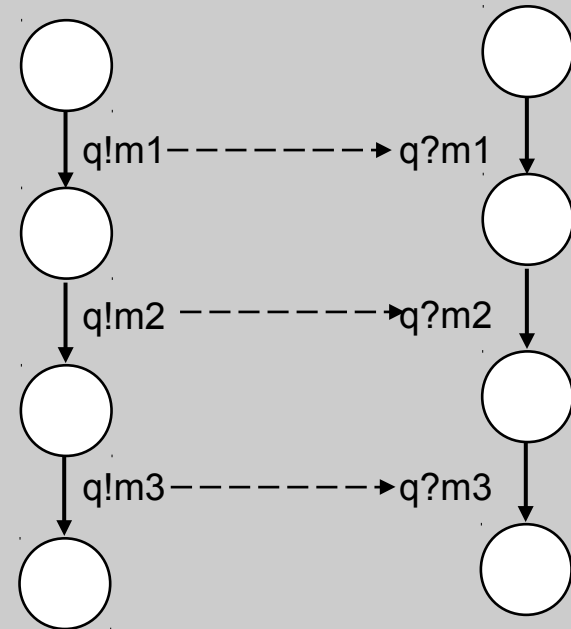
```
ch!ack(0);
```

```
ch?ack(seqno)
```

# asynchronous and synchronous message passing



asynchronous  
 messages can be buffered for  
 later retrieval – up to the capacity  
 of the channel  
 sender blocks when channel is full  
 receiver blocks when channel  
 is empty



synchronous  
 with channel capacity 0, as in:  
`chan ch = [0] of { mtype };`  
 can only perform an rv handshake  
 not store messages  
 sender blocks until matching receiver  
 is available and vice versa

# rendezvous channels

- rendezvous message passing
  - the size of the channel is declared to be zero
  - a send operation is enabled (a send offer) iff there is a matching receive operation that can be executed simultaneously, with all constant fields matching
  - on a match, both send and receive are executed *atomically*
- *example:*

```
chan ch = [0] of {bit, byte};
```

– P offers: `ch!1,3+7`

– Q accepts: `ch?1,x`

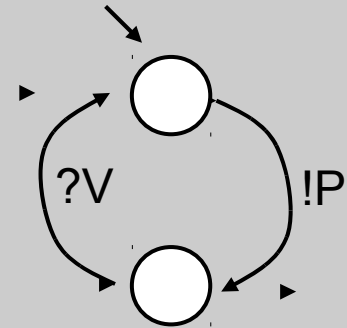
– after the rendezvous handshake completes, `x` has value 10

message must match value 1 in the first message field, but can accept any value in the second message field (x)



# example: modeling a semaphore

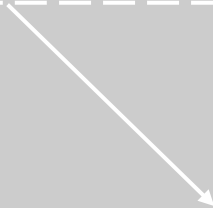
```
mtype = { P, V };  
  
chan sema = [0] of { mtype };  
  
active proctype semaphore()  
{  
L:  sema!P -> sema?V; goto L  
}  
  
active [5] proctype user()  
{  
L:  /* non-critical */  
    sema?P ->  
    /* critical */  
    sema!V;  
    goto L  
}
```



P – passeren (Dutch)  
V - vrijgeven

# other operations on channels

- `len(q)` returns the number of messages in `q`
- `empty(q)` true when `q` is currently empty
- `full(q)` true when `q` is filled to capacity
- `nempty(q)` added to support optimization
- `nfull(q)` added to support optimization



used instead of `!empty(q)` or `!full(q)`  
the parser makes this easy to remember:  
it rejects the negated forms

## brackets, braces channel poll

- $q?[n,m,p]$ 
  - is now a side-effect free Boolean *expression*
  - evaluates to *true* precisely when  $q?n,m,p$  is executable, but has *no* effect on  $n,m,p$  and does *not* change contents of  $q$
- $q?\langle n,m,p \rangle$ 
  - is executable iff  $q?n,m,p$  is executable; has the *same* effect on  $n,m,p$  as  $q?n,m,p$ , but does *not* change contents of  $q$
- $q?n(m,p)$ 
  - alternative notation for standard receive; same as  $q?n,m,p$
  - sometimes useful for separating type from args

# the scope of a chan declaration

- the name of a channel can be local or global, but the channel itself is always a global object....
- this makes obscure things like this work:

```
chan x = [3] of { chan }; /* global handle, visible to both A and B */

active proctype A()
{
    chan a;          /* uninitialized local channel */

    x?a;            /* get channel id, provided by process B */
    a!x             /* and start using b's channel! */
}

active proctype B()
{
    chan b = [2] of { chan }; /* initialized local channel */

    x!b;            /* make channel b available to A */
    b?x;            /* value of x doesn't really change */
    0               /* avoid death of B, or else b disappears */
}
}
```

# macros – the cpp preprocessor

- all Spin models are by default processed by the standard C preprocessor for *file-inclusion* and *macro expansion*
- typical uses

- constants

```
#define MAXQ      2
chan q = [MAXQ] of { mtype, chan };
```

```
or:
spin -DMAXQ=2 model
```

- macros

```
#define RESET(a) \
    atomic { a[0]=0; a[1]=0; a[2]=0; a[3]=0 }
```

- conditional  
code

```
#define LOSSY 1
...
#ifdef LOSSY
    active proctype Daemon() { /* steal messages */ }
#endif
...
#if 0
    comments
#endif
```

# the scope of a data object

- there are only *two* levels of scope:
  - global (data visible to all active processes)
  - local (data visible to only the process that contains the declaration)
    - there is no sub-scope (e.g., for blocks or *inlines*)
    - the scope of a local variable is *always* the complete proctype body

```
active proctype main()
{
  int x, y; /* x and y declared in outer block */
  {
    /* a block: a statement sequence */
    int y, z; /* error, redeclaration of y */
    x++; y++; z++ /* original y is used */
  }; /* note semi-colon placements */

  /* variable z remains in scope! */
  printf("y = %d, z = %d\n", y, z) /* prints: 1, 1 */
}
```

# defining control flow

- 5 ways to define control flow structures in proctypes:
  - the obvious: semi-colons, gotos and labels
  - structuring aids:
    - `inlines`
    - `macros`
  - atomic sequences, making things indivisible:
    - `atomic { ... }`
    - `d_step { ... }`
  - non-deterministic selection and iteration
    - `if .. fi`
    - `do .. od`
  - escape sequences, for error handling/interrupts:
    - `{ ... } unless { ... }`

# non-deterministic selection

```
if
:: guard1 -> stmt1.1; stmt1.2; stmt1.3; ...
:: guard2 -> stmt2.1; stmt2.2; stmt2.3; ...
:: ...
:: guardn -> stmtn.1; stmtn.2; stmtn.3; ...
fi
```

- if at least one guard is executable, the if statement is *executable*
- if more than one guard is executable, one is selected non-deterministically
- if none of the guard statements is executable, the if statement *blocks*
- *any* type of basic or compound statement can be used as a guard

inspired by Dijkstra's guarded command language,  
but the semantics differ: the if does not abort when all guards are unexecutable:  
it blocks execution instead

Recommended reading:  
E.W. Dijkstra,  
Guarded commands, nondeterminacy, and formal derivation of programs.  
Comm. ACM, Aug. 1975, Vol. 18, No. 8, pp. 453-457.



# the if-statement

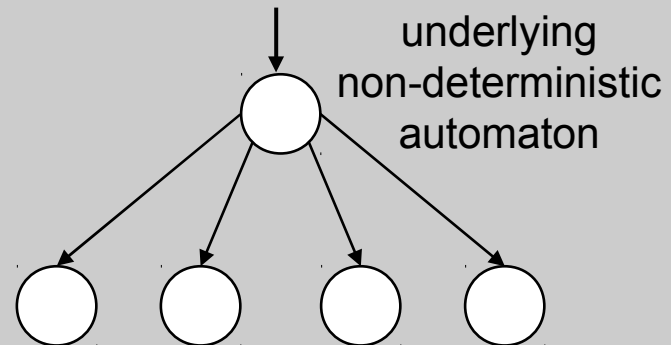
```
/* find the max of x and y */  
if  
:: x >= y -> m = x  
:: x <= y -> m = y  
fi
```

```
/* pick a number 0..3 */  
if  
:: n=0  
:: n=1  
:: n=2  
:: n=3  
fi
```

non-deterministically assigns  
a value to  $n$  in the range 0..3

```
if  
:: (n % 2 != 0) -> n = 1  
:: (n >= 0) -> n = n-2  
:: (n % 3 == 0) -> n = 3  
:: else /* -> skip */  
fi
```

the else guard is executable iff *none*  
of the other guards is executable.



# the predefined *expression* 'else'

where in C one writes:

```
if (x <= y)
    x = y-x;
y++;
```

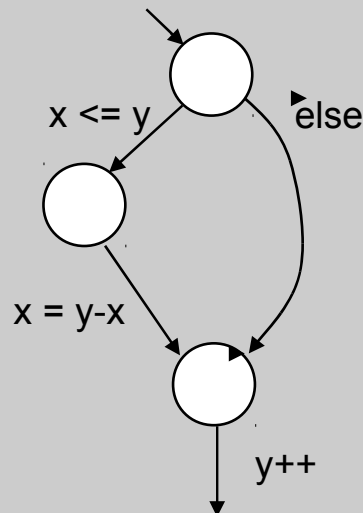
i.e., omitting the 'else'

in Promela this is written:

```
if
:: (x <= y) -> x = y-x
:: else
fi;
y++
```

no need to add  
"-> skip"

i.e., the 'else' part cannot be omitted



in this case 'else' evaluates to:  
 $!(x \leq y)$

the else clause always has to be explicitly present without it, the if- statement would block until  $(x \leq y)$  becomes true (it then gives only *one* option for behavior)

# timeout

```
if
:: q?msg -> ...
:: q?ack -> ...
:: q?err -> ...
:: timeout -> ...
fi
```

checking for bad timeouts:  
spin -Dtimeout=true model

wait until an expected message arrives, or recover when the system as a whole gets stuck (e.g., due to message loss)

Q: could you use 'else' instead of 'timeout' in this context?

# timeout and else

- timeout and else are strangely related
  - both are predefined Boolean expressions
  - they evaluate to *true* or *false*, depending on context

- **else** is *true* iff  
no other statement in the same *process* is executable
- **timeout** is *true* iff  
no other statement in the same *system* is executable

- a timeout can be seen as a system level else
  - *else* cannot be combined with other conditionals
  - *timeout* can be combined, e.g. as in (timeout && a > b)