DATA MINING 2 Time Series Classification

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Time Series Classification

- Given a set X of n time series, $X = \{x_1, x_2, ..., x_n\}$, each time series has m ordered values $x_i = \langle x_{t1}, x_{t2}, ..., x_{tm} \rangle$ and a class value c_i .
- The objective is to find a function f that maps from the space of possible time series to the space of possible class values.
- Generally, it is assumed that all the TS have the same length m.

KNN Classification

 The most widely used and effective approach for TSC consists in using KNN on the raw time series.

• Pros:

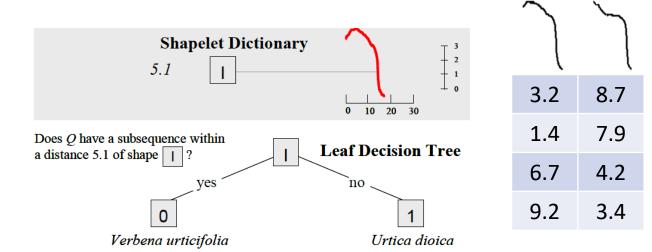
- Simple
- Dynamic Time Warping gives much better results than Euclidean distance on many problems.

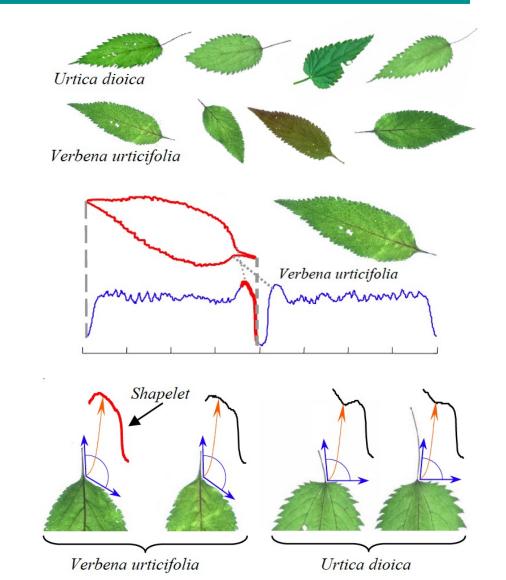
• Cons:

- KNN is a lazy classifier and computationally expensive on its own
- Dynamic Time Warping is very very slow to calculate

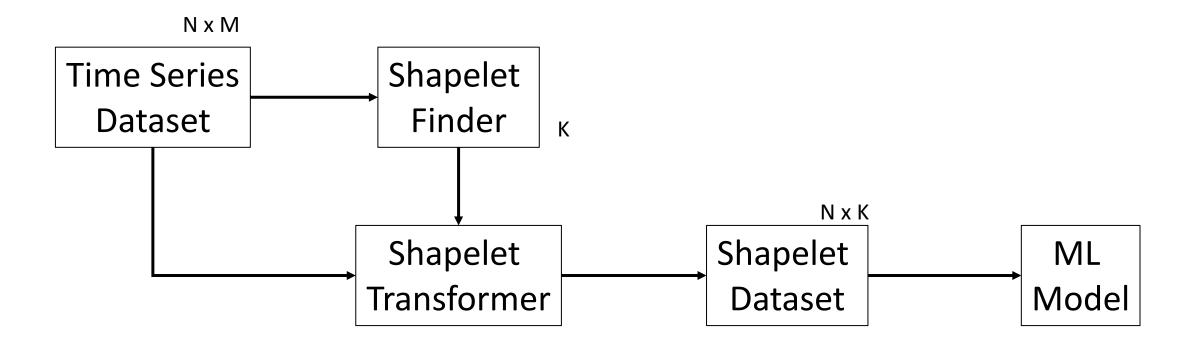
Shapelet-based Classification

- 1. Represent a TS as a vector of distances with representative subsequences, namely shapelets.
- 2. Use it to as input for machine learning classifiers.



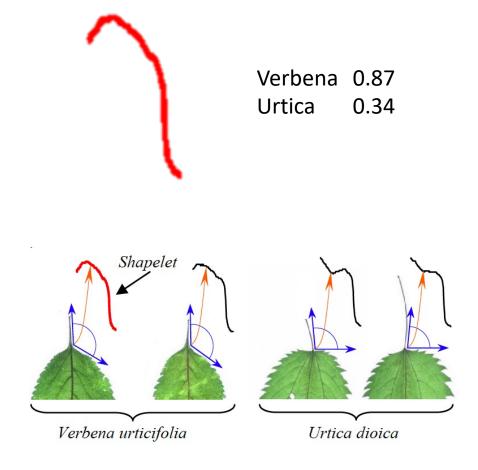


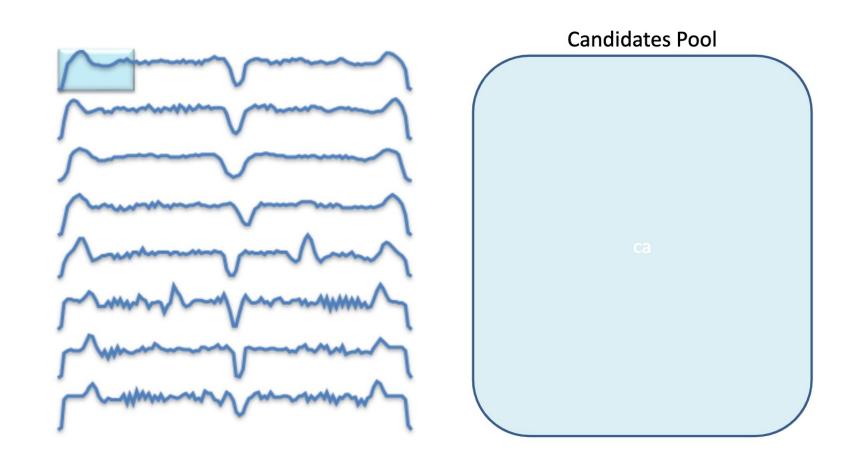
Shapelet-based Classifiers

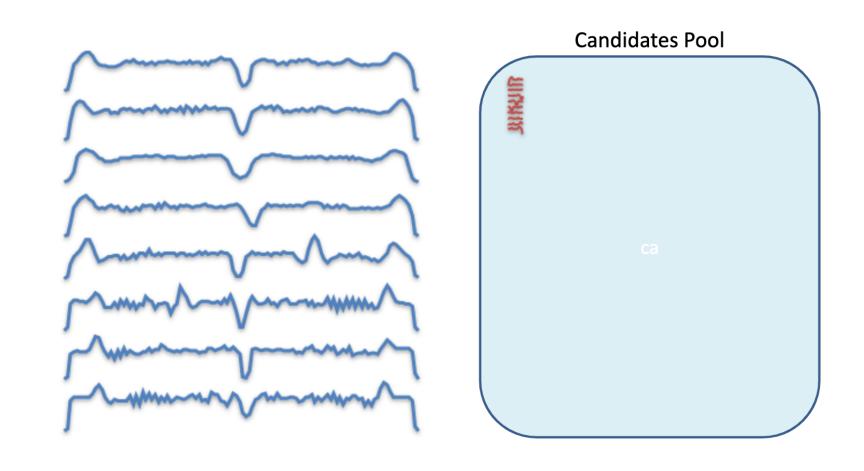


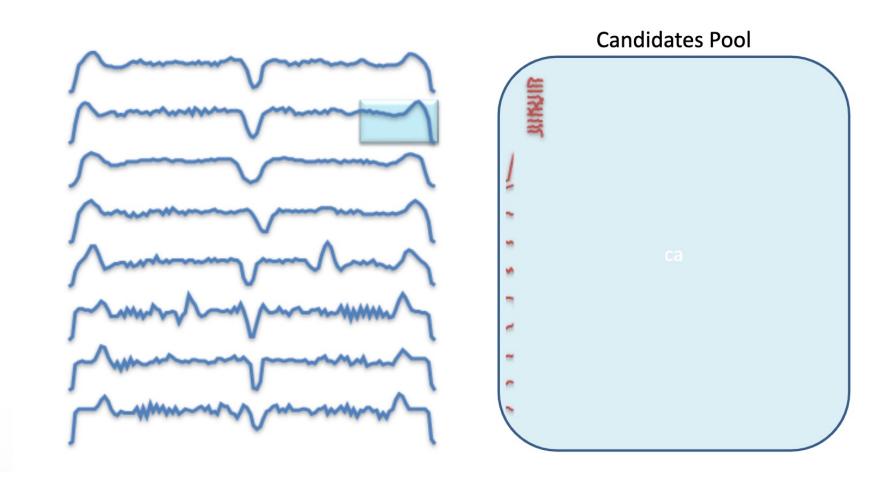
Time Series Shapelets

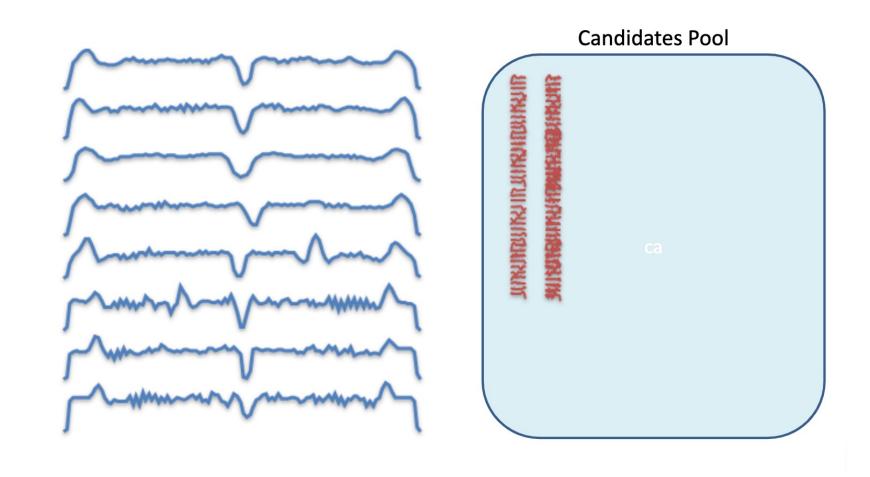
- Shapelets are TS subsequences which are maximally representative of a class.
- Shapelets can provide interpretable results, which may help domain practitioners better understand their data.
- Shapelets can be significantly more accurate/robust because they are *local features*, whereas most other state-of-theart TS classifiers consider *global features*.

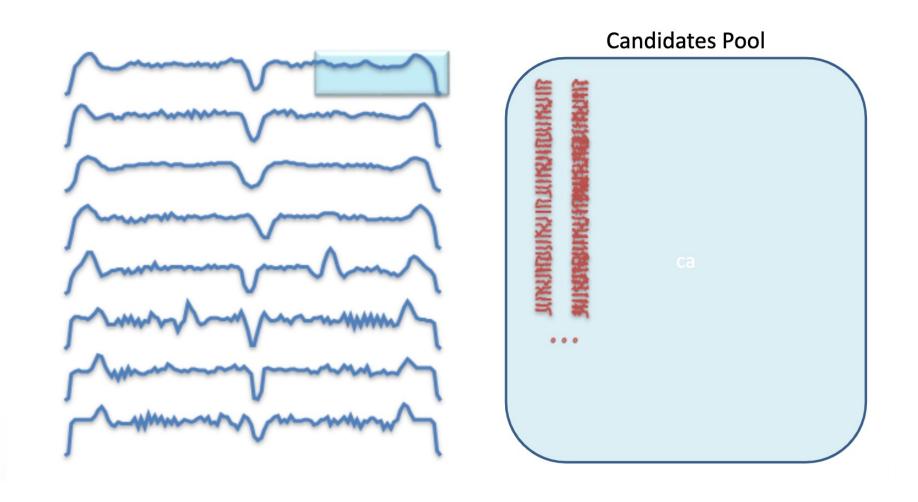






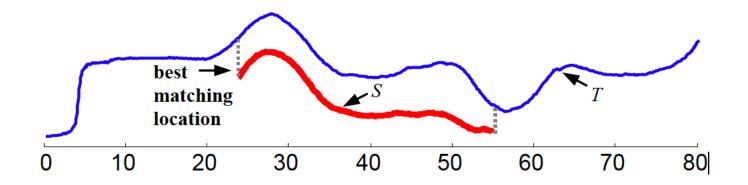






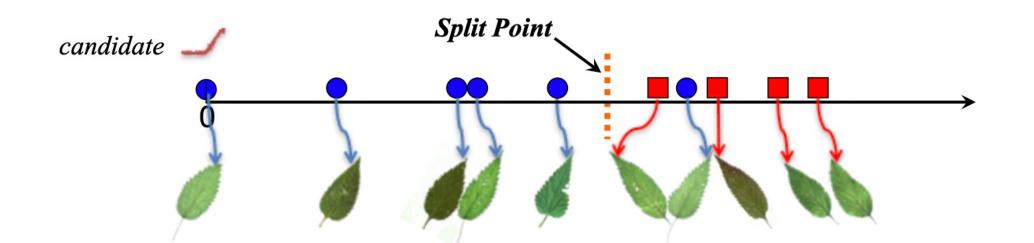
Distance with a Subsequence

- Distance from the TS to the subsequence SubsequenceDist(T, S) is a distance function that takes time series T and subsequence S as inputs and returns a nonnegative value d, which is the distance from T to S.
- SubsequenceDist(T, S) = min(Dist(S, S')), for $S' \in S_T^{|S|}$
- where $S_T^{|S|}$ is the set of all possible subsequences of T
- Intuitively, it is the distance between S and its best matching location in T.

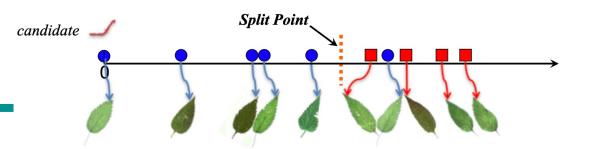


Testing The Utility of a Candidate Shapelet

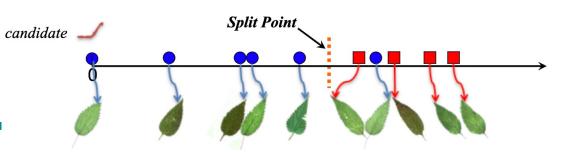
- Arrange the TSs in the dataset D based on the distance from the candidate.
- Find the optimal split point that maximizes the information gain (same as for Decision Tree classifiers)
- Pick the candidate achieving best utility as the shapelet



Entropy



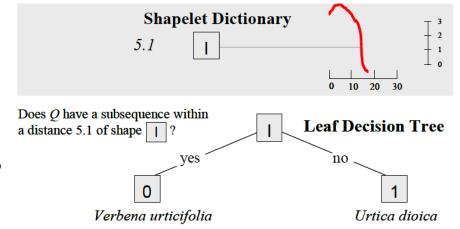
- A TS dataset D consists of two classes, A and B.
- Given that the proportion of objects in class A is p(A) and the proportion of objects in class B is p(B),
- The **Entropy** of D is: I(D) = -p(A)log(p(A)) p(B)log(p(B)).
- Given a strategy that divides the D into two subsets D_1 and D_2 , the information remaining in the dataset after splitting is defined by the weighted average entropy of each subset.
- If the fraction of objects in D_1 is $f(D_1)$ and in D_2 is $f(D_2)$,
- The total entropy of D after splitting is $\hat{I}(D) = f(D_1)I(D_1) + f(D_2)I(D_2)$.



Information Gain

- Given a certain split strategy sp which divides D into two subsets D_1 and D_2 , the entropy before and after splitting is I(D) and $\hat{I}(D)$.
- The **information gain** for this splitting rule is:
- $Gain(sp) = I(D) \hat{I}(D) =$
- = $I(D) f(D_1)I(D_1) + f(D_2)I(D_2)$.
- We use the distance from T to a shapelet S as the splitting rule sp.

Split point distance from shapelet = 5.1



Problem

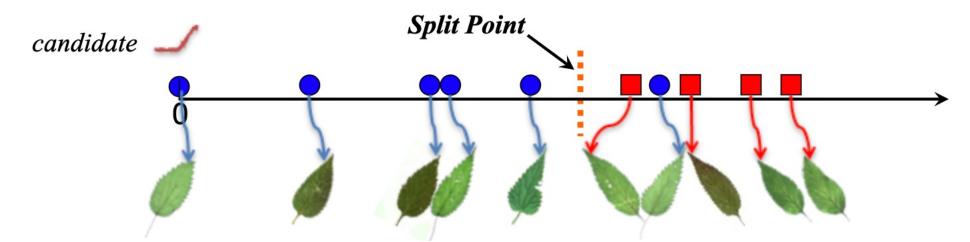
• The total number of candidate is

$$\sum_{l=MINLEN}^{MAXLEN} \sum_{T_i \in D} (|T_i| - l + 1)$$

- For each candidate you have to compute the distance between this candidate and each training sample
- For instance
 - 200 instances with length 275
 - 7,480,200 shapelet candidates

Speedup

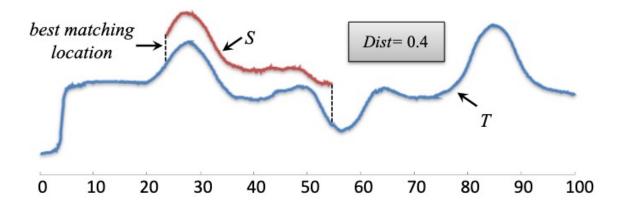
- Distance calculations form TSs to shapelet candidates is expensive.
- Reduce the time in two ways
- Distance Early Abandon
 - reduce the distance computation time between two TS
- Admissible Entropy Pruning
 - reduce the number of distance calculations

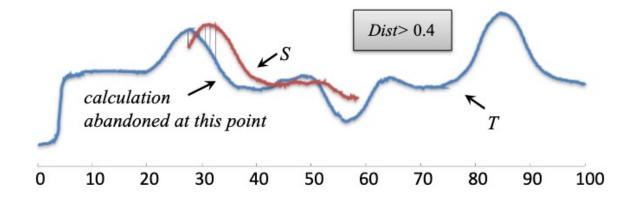


Distance Early Abandon

• We only need the minimum distance.

- Method
 - Keep the best-so-far distance
 - Abandon the calculation if the current distance is larger than best-so-far.

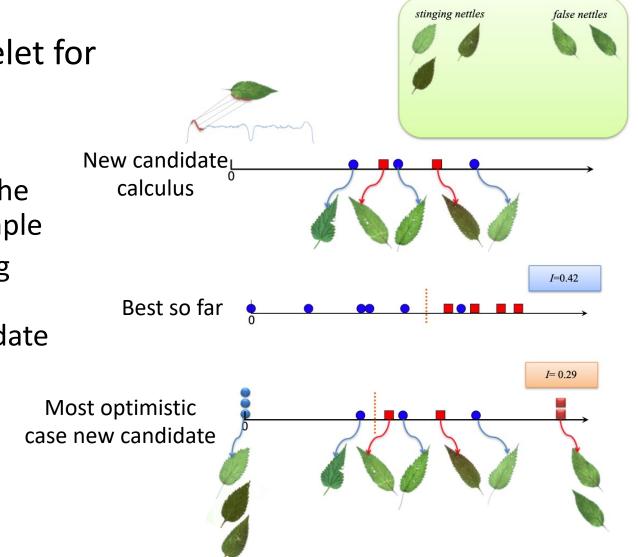




Admissible Entropy Pruning

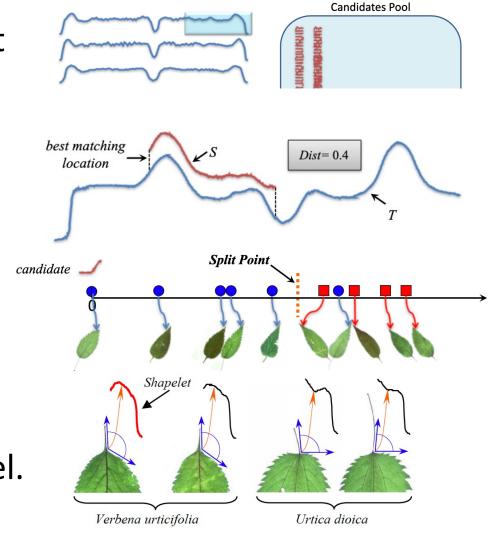
 We only need the best shapelet for each class

- For a candidate shapelet
 - We do not need to calculate the distance for each training sample
 - After calculating some training samples, the upper bound of information gain < best candidate shapelet
 - Stop calculation
 - Try next candidate



Shapelet Summary

- 1. Extract all possible subsequences of a set given lengths (candidate shapelets)
- 2. For each candidate shapelet
 - Calculate the distance with each time series keeping the minimum distance (best alignment)
 - 2. Evaluate the discriminatory effect of the shapelet through the Information Gain
- 3. Return the *k* best shapelets with the highest Information Gain.
- 4. Transform a dataset and train a ML model.



An Alternative Way for Extracting Shapelets

• The minimum distances (M) between Ts and Shapelets can be used as predictors to approximate the TSs label (Y) using a linear model (W):

$$\hat{Y}_i = W_0 + \sum_{k=1}^K M_{i,k} W_k, \quad \forall i \in \{1, \dots, I\}$$

A logistic regression loss can measure the quality of the prediction:

$$\mathcal{L}(Y, \hat{Y}) = -Y \ln \sigma(\hat{Y}) - (1 - Y) \ln \left(1 - \sigma(\hat{Y})\right)$$

• The objective is to minimize a regularized loss function across all the instances (I):

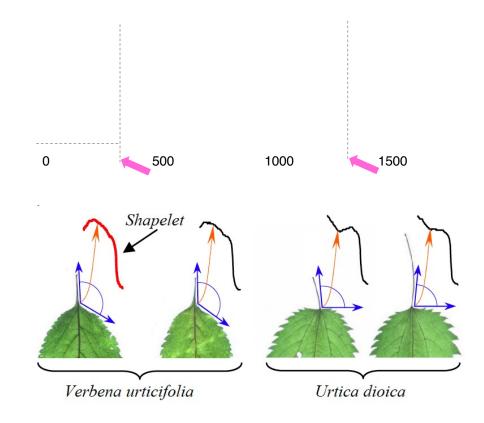
$$\underset{S,W}{\operatorname{argmin}} \ \mathcal{F}(S,W) = \underset{S,W}{\operatorname{argmin}} \sum_{i=1}^{I} \mathcal{L}(Y_i, \hat{Y}_i) + \lambda_W ||W||^2$$

 We can find the optimal shapelet for the objective function in a NN fashion by updating the shapelets in the minimum direction of the objective, hence the first gradient.
 Similarly, the weights can be jointly updated towards minimizing the objective function.

Motif/Shapelet Summary

• A **motif** is a repeated pattern/subsequence in a given TS.

 A shapelet is a pattern/subsequence which is maximally representative of a class with respect to a given dataset of TSs.



References

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Matrix Profile I: All Pairs Similarity Joins for Time Series A Unifying View that Includes Motifs, Discords and Shapelets

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I. INTRODUCTION

The all-pairs-similarity-search (also known as similarity on) problem comes in several variants. The basic task is this: Given a collection of data objects, retrieve the nearest neighbor for each object. In the text domain the algorithm has

ressure once a minute. After a year, we have ime series of length 525,600. A plant manager may wish to do a similarity self-join on this data with week-long subsequences a similarly self-join on this state with week-tong subsequences, and the properties of the properties

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Deep learning for time series classification

Abstract Time Series Classification (TSC) is an important and challe With the increase of time series data availability, hundreds of TSC a Among these methods, only a few have considered Deep Neural Net task. This is surprising as deep learning has seen very successful appli have indeed revolutionized the field of computer vision especially w architectures such as Residual and Convolutional Neural Networks. data such as text and audio can also be processed with DNNs to read for document classification and speech recognition. In this article, the-art performance of deep learning algorithms for TSC by preser most recent DNN architectures for TSC. We give an overview of the applications in various time series domains under a unified taxonor provide an open source deep learning framework to the TSC communi archive) and 12 multivariate time series datasets. By training 8,73 time series datasets, we propose the most exhaustive study of DNNs

Keywords Deep learning - Time series - Classification - Review

- tuning spatial access methods and/or hash function While our exact algorithm is extremely scalable,
 - While our enter algorithm is extremely scalable, for extremely large datasets we can compute the results in an anytime fishion, allowing ultra-fast approximate solutions. Having computed the similarity join for a dataset, we can incrementally update it very efficiently. In many domains this means we can effectively maintain exect joins on streaming data forever. Our method provides of the property of the con-tract improvides the design of the contract of the next improvide task of the contract of the con-tract improvide task in this down is a lower improvided to un also think in computer our all clitable, both on

 - Our algorithm is embarrassingly parallelizable, both on multicore processors and in distributed existence

Time Series Shapelets: A New Primitive for Data Mining

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for most time series problems. While this may be considered good new, piven the simplicity of implementing the nearest neighbor algorithm, there are some negative consequences of this. First, the nearest neighbor algorithm requires storing and searching the entire dataset, resulting in a time and space complexity that limits its applicability, opeically one resource-imitted sensors. Second, beyond mere classification accuracy, we often wish to gain some minght note the day.

ime series shapelet primitives can be interpretable, more accura

Categories and Subject Descriptors

General Terms

. INTRODUCTION

In INTRODUCTION
While the last decade has seen a lurge interest in time series classification, to date the most accurate and robust method is the simple nearest neighbor algorithm [412][414]. While the nearest neighbor algorithm has the advantages of simplicity and not requiring extensive parameter tuning, it does have several important disadvantages. Chief among these are its space and time equirements, and the fact that it does not tell us anything about only a particular object was assigned to a particular class.

In this work we present a novel time series data mining primitive called five nevine abopted: Informally, shapelets are time series subsoppences which are is some sense maximally representative of a class. While we believe thispelets can have many uses in data mining, one obvious implication of them is to mitigate the two weaknesses of the nearest neighbor algorithm noted algorithm to weaknesses of the nearest neighbor algorithm noted algorithm.

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some time to consider a detailed motivating example. Figure shows some examples of leaves from two classes, Urica dioic (stinging nettles) and Verbena writcifolia. These two plants are commonly confused, hence the colloquial name "false nettle" fo Verbena urricifolia.



appose we wish to build a classifier to distinguish thes

plants; what features should we use? Since the intra-variability color and size within each class completely dwarfs the inte-



classification, clustering and outlier obectoon or snapes in receivers [8]. However, here we find that using a nearest neighboclassifier with either the (rotation invariant) Euclidean distance of Dynamic Time Warping (DTW) distance does not significant outperform random guessing. The reason for the pot performance of these otherwise very competitive classifiers seen. to be due to the fact that the data is somewhat noisy (i.e. insect bites, and different stem lengths), and this noise is enough to

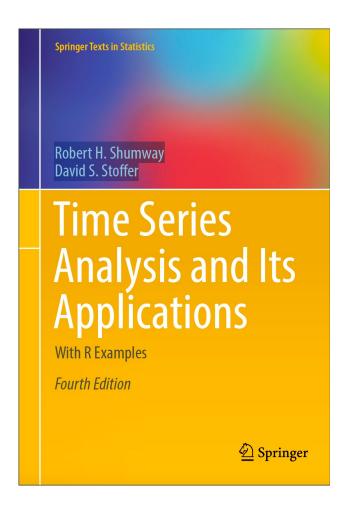
During the last two decades. Time Series Classification (TSC) has been considered as one of th most challenging problems in data mining (Yang and Wu, 2006; Esling and Agon, 2012). With the increase of temporal data availability (Silva et al., 2018), hundreds of TSC algorithms have been proposed since 2015 (Bagnall et al., 2017). Due to their natural temporal ordering, time series data are present in almost every task that requires some sort of human cognitive process (Längkvist et al., 2014). In fact, any classification problem, using data that is registered taking into account some notion of ordering, can be cast as a TSC problem (Cristian Borges Gamboa, 2017). Time series are encountered in many real-world applications ranging from electronic health records (Rajkomar et al., 2018) and human activity recognition (Nweke et al., 2018; Wang et al., 2018) to acoustic scene classification (Nwe et al., 2017) and cyber-security (Susto et al., 2018). In addition, the diversity of the datasets' types in the UCR/UEA archive (Chen et al., 2015b; Bagnall et al., 2017) (the largest repository of time series datasets) shows the different applications of the TSC problem

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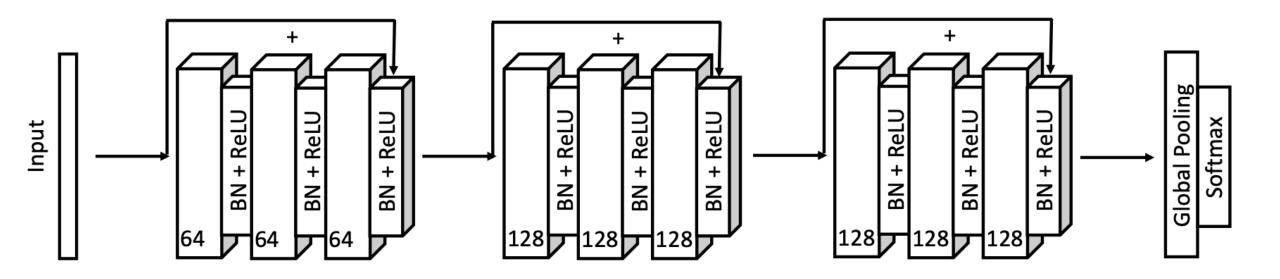


TSC State-of-The-Art

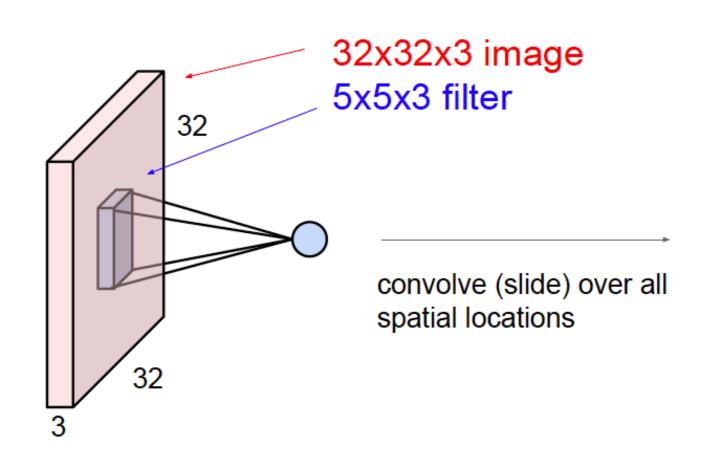


ResNet

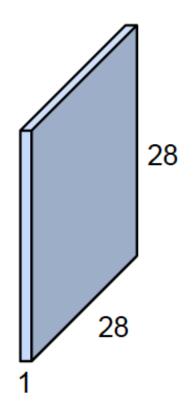
- Three consecutive blocks, comprised of three convolutional layers, connected by residual 'shortcut' connections.
- The blocks are followed by global average pooling and softmax layers to form features and subsequent predictions.



Convolution Layer

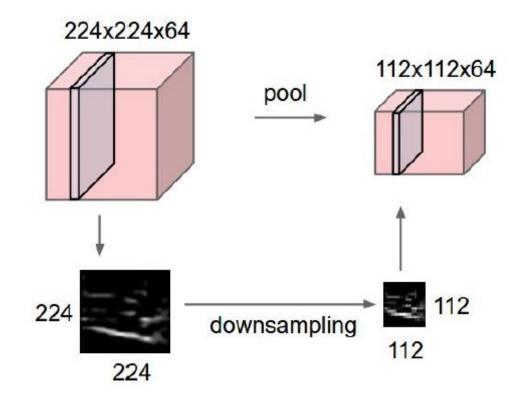


activation map

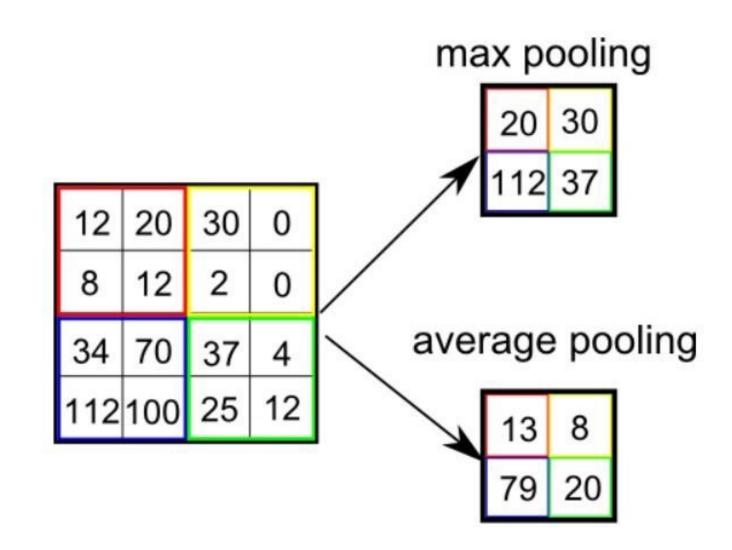


Pooling Layer

- Makes the representations smaller and more manageable
- Operates over each activation map independently



MaxPooling and AvgPoling



InceptionTime

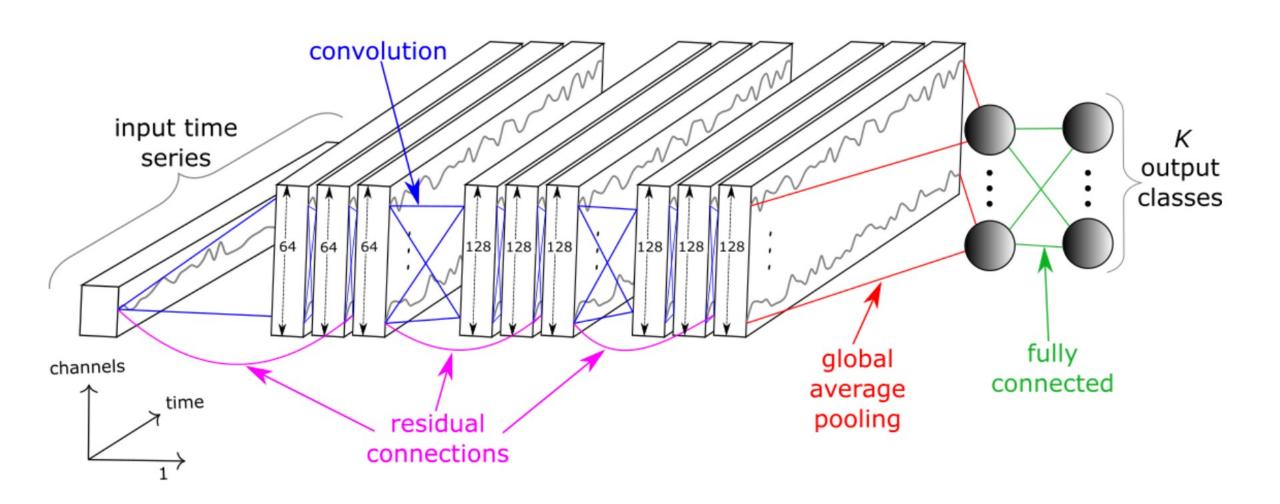
Neural network ensemble consisting of five Inception networks.

For each inception network:

- three Inception modules (6 blocks by default)
- global averaging pooling
- fully-connected layer with the softmax activation function.

Each Inception module consists of convolutions with kernels of several sizes followed by batch normalization and the rectified linear unit activation function.

InceptionTime



TapNet

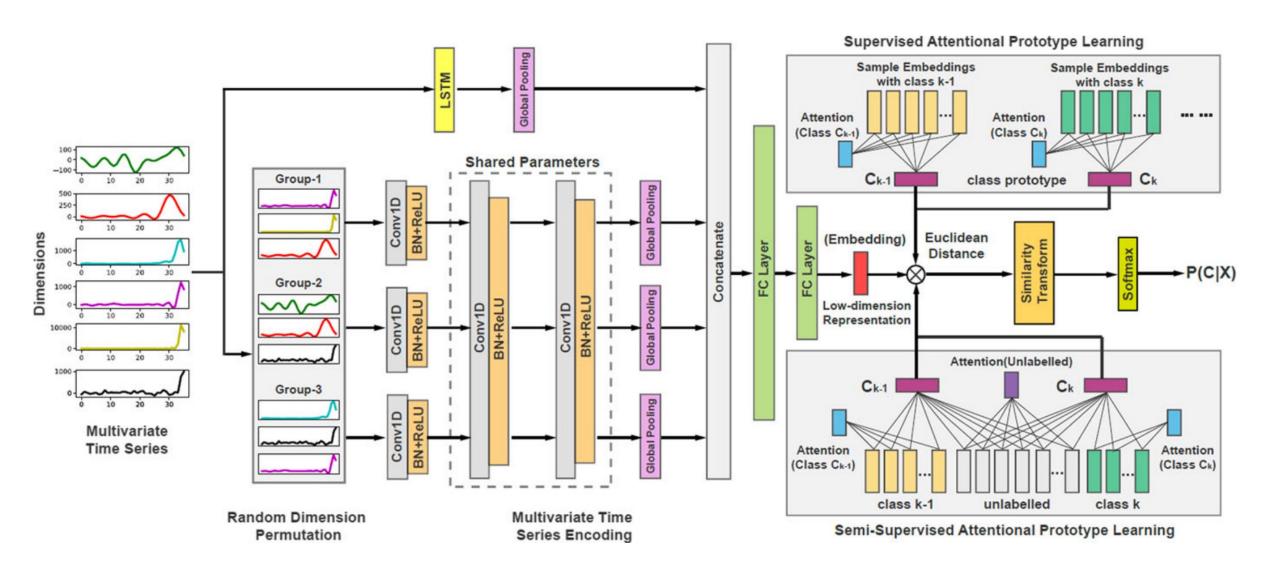
Draws on the strengths of both traditional and deep learning approaches:

- deep learning approaches -> excel at learning low dimensional features without the need for embedded domain knowledge, whereas
- traditional approaches -> work well on small datasets.

3 distinct modules:

- Random Dimension Permutation: produce groups of randomly selected dimensions with the intention of increasing the likelihood of learning how combinations of dimension values effect class value.
- Multivariate Time Series Encoding:
 - 3 sets of 1d convolutional layers followed by batch normalisation
 - the raw data is also passed through an LSTM and global pooling layer
- Attentional Prototype Learning: used for unlabelled data

TapNet



Canonical Interval Forest (CIF)

Ensemble of time series tree classifiers built using the 22 Canonical Time-Series Characteristics (Catch22) features and simple summary statistics (mean, stdev, slope).

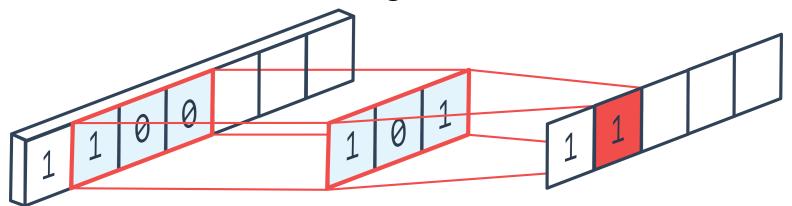
For each tree, CIF:

- samples k time series intervals of random position and length;
- subsamples 8 of the 25 features randomly;
- calculates the features for each interval, concatenates them to form a new data set;
- builds a decision tree on the feature-transformed dataset.

ROCKET

ROCKET (Random Convolutional Kernel Transform) uses a large number of random convolutional kernels to transform the time series:

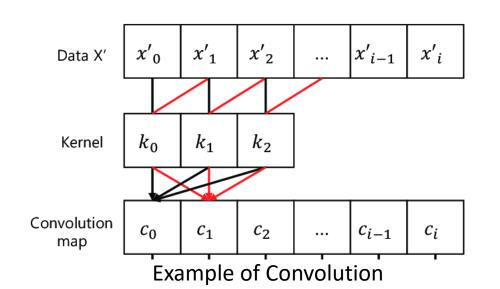
- all the parameters of all the kernels are randomly generated from fixed distributions;
- the transformed features are used to train a linear classifier (Logistic Regression or Ridge Regression Classifier);
- the combination of Rocket and logistic regression forms a single-layer convolution with random kernel weights with a trained softmax layer.

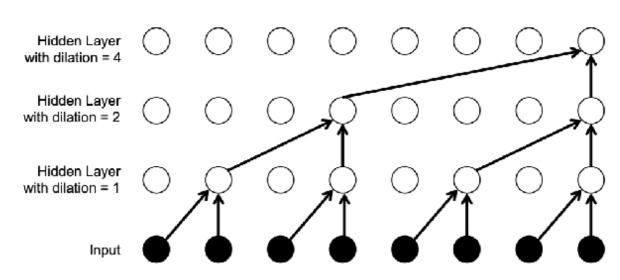


ROCKET vs. CNN

CNNs use <u>trainable</u> filters/kernels optimized by stochastic gradient descent to find patterns in the input data. Rocket differs in the following ways:

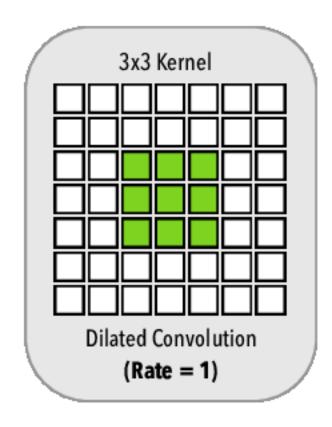
- Only a <u>single</u> layer containing a very large number of <u>random</u> kernels.
- Variety of kernels: each kernel has random length, dilation, and padding, weights and biases.

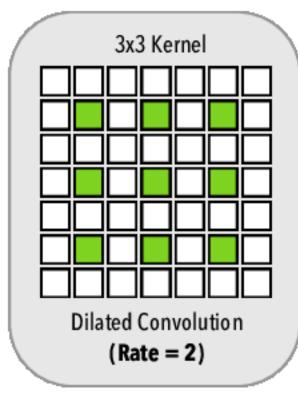


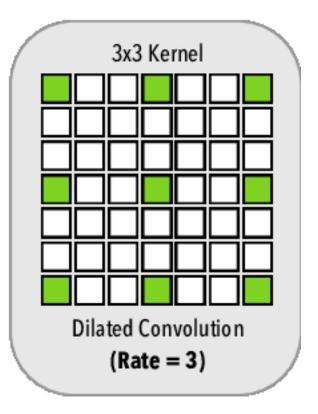


Example of Dilated Convolution

Dilated Convolution Kernels







ROCKET vs. CNN

- In CNNs kernel <u>dilation increases exponentially with depth</u>. Rocket sample dilation randomly for each kernel, capturing patterns at different frequencies and scales.
- Rocket uses the maximum value of the resulting feature maps (~global max pooling), and the proportion of positive values (proportion of the input which matches a given pattern).

- The only hyperparameter for Rocket is the number of kernels, k.
 - k handles the trade-off between classification accuracy and computation time

MINIROCKET

MiniRocket removes almost all randomness from Rocket, and dramatically speeds up the transform.

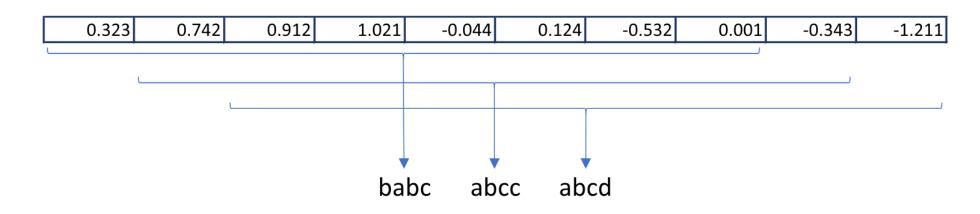
- Length: uses kernels of length 9.
- Weights: restricted to two values, $\alpha = -1$ and $\beta = 2$.
- Kernels: there are 512 possible two-valued kernels of length 9. Only subset of 84 is used.
- Bias: drawn from the quantiles of the convolution output for the entire training set (rather than a single, randomly-selected training example)
- Dilation: Each kernel is assigned the same fixed set of dilations, adjusted to the length of the input time series. The maximum number of dilations per kernel is 32
- Padding: half the kernel/dilation combinations use padding, and half do not.
- Features: only proportion of positive values.

COTE / HIVE-COTE / TS-CHIEF

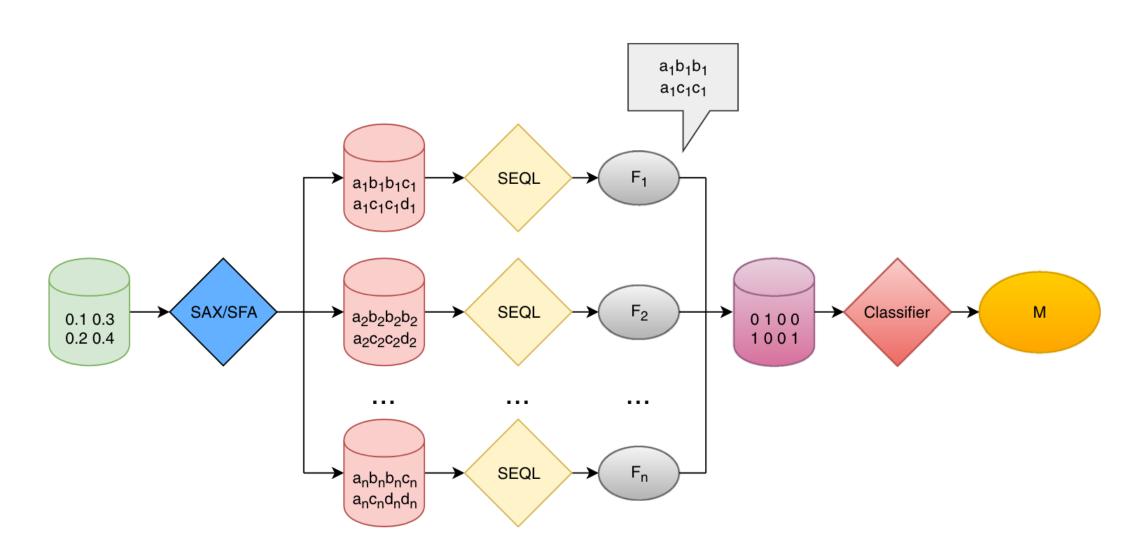
- Collective of Transformation-Based Ensembles (COTE) combines 35 classifiers over four data representations (similarity measures, shapelet-transform, autocorrelation features, power spectrum).
- Hierarchical Vote Collective of Transformation-Based Ensembles (HIVE-COTE) is an extension of COTE including more classifiers and a <u>hierarchical voting procedure</u>.
- Time Series Combination of Heterogeneous and Integrated Embedding Forest (TS-CHIEF) builds a random forest of decision trees whose splitting functions are time series specific and based on similarity measures, dictionary (bag-of-words) representations, and interval-based transformations.

MR-SEQL

- The data is discretized into sequences of words via either Symbolic Aggregate Approximation (SAX) or SFA, using a sliding window.
- The most discriminative symbols are extracted using a SEQuence Learner algorithm.
- The dataset is transformed in presence/absence of subsequences (similar to a shapelet transform)
- A linear (interpretable) model is trained on this new representation



MR-SEQL



Ranking Multivariate TSC algorithms

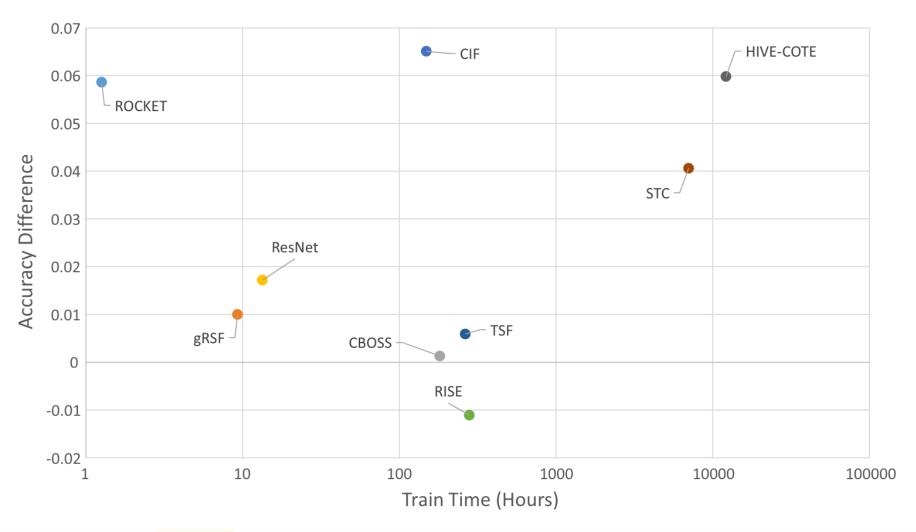
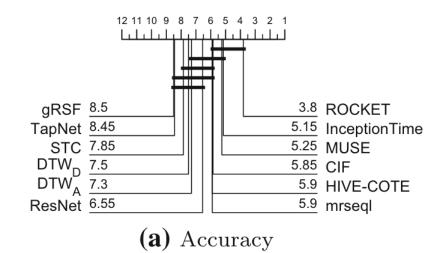
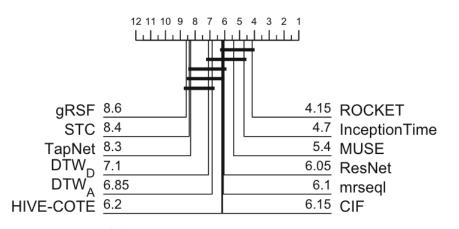


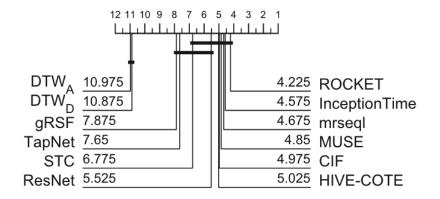
Fig. 10 Average difference in accuracy to DTW_D versus train time for 9 MTSC algorithms

Ranking Multivariate TSC algorithms

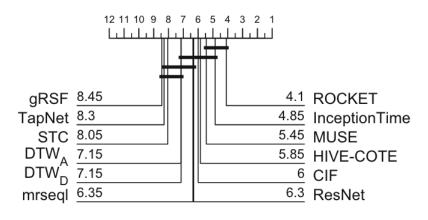




(c) Balanced Accuracy



(b) AUROC



(d) F1

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